



La Sapienza

Università degli Studi di Roma

Automatic Composition of e-Services that Export their Behavior

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Basics on e-Services

- e-Service is **interactive program**
typically delivered over the Internet
- ... that **exports its behavior** ...
i.e., its process
- ... in terms of an **abstract description**
e.g., state chart, UML state-transition diagram, FSM
- A **client selects and interacts** with it according to the description exported

Community of e-Services

- A **community** of e-Services is
 - a **set** of e-Services ...
 - ... that share implicitly a *common understanding* on a **common set of actions** ...
 - ... and export their **behavior** using this **common set of actions**
- A **client** specifies needs as e-Service behavior using the **common set of actions** of the community

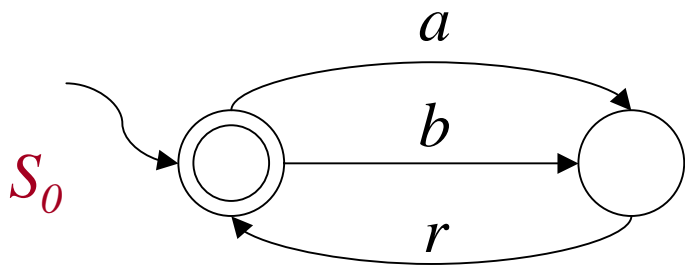
e-Service exports its behavior ...

Many possible ways. **In this talk...**

- Behavior modeled by a **finite state machines**
core of state chart, UML state-transition diagram, etc.
- In fact using a FSM we compactly describe all possible sequences of **deterministic** (atomic) **actions**: tree of all possible sequences of actions
- **Data** produced by actions **not explicitly** modeled
data are used by the client to choose next action

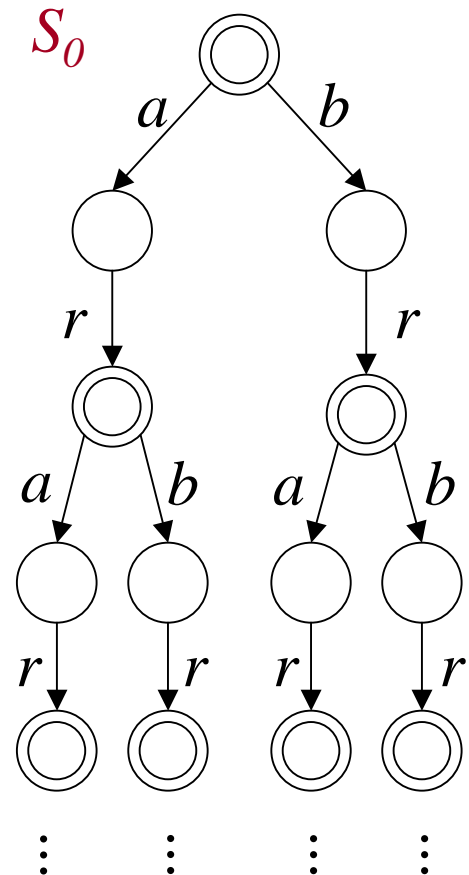
e-Service as execution tree

*Required behavior represented as a FSM
(a Moore machine)*



a: “search by author (and select)”
b: “search by title (and select)”
r: “listen (the selected song)”

*Execution tree
(obtained by FSM unfolding)*



e-Service as execution tree

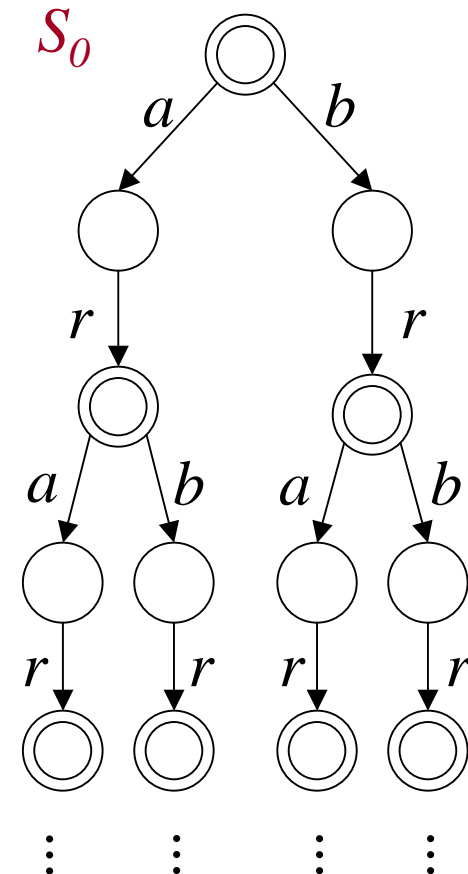
- **Nodes:** *history* (sequence) of actions executed so far
- **Root:** no action yet performed
- **Successor node $x \cdot a$ of x :** action a can be executed after the sequence of action x
- **Final nodes:** the e-Service can terminate

a : “search by author (and select)”

b : “search by title (and select)”

r : “listen (the selected song)”

*Execution tree
(obtained by FSM unfolding)*



e-Service composition

- Added value of the community...

...when a client request cannot be satisfied by any available e-Service, it may still be possible to satisfy it by combining "pieces" of e-Services in the community

- Two issues arise:
 - support for **synthesizing composition**:
 - automatic synthesis of a **coordinating program (composition)** ...
 - ... that realizes the **target e-Service** (client request) ...
 - ... by suitably **coordinating** available e-Services

addressed here

- support for **orchestration**: execution of the coordinating program

not addressed here

Formalizing e-Service composition

Composition:

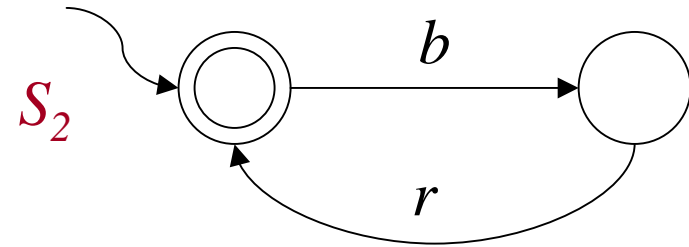
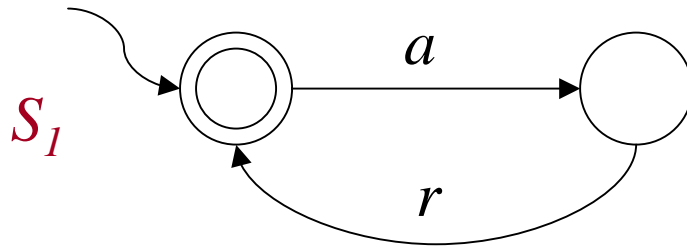
- coordinating program ...
- ... that realizes the target e-Service ...
- ... by suitably coordinating available e-Services

Composition can be formalized as:

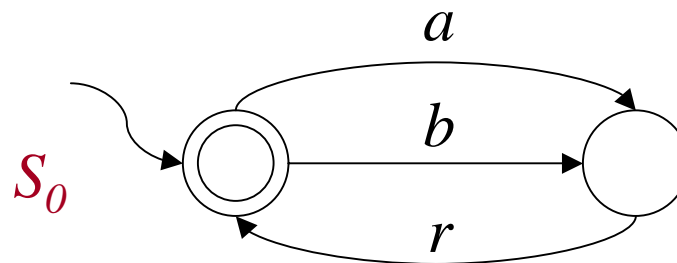
- a **labeling of the execution tree** of the target e-Service such that ...
- ... each **action** in the execution tree is labeled by the community e-Service that executes it ...
- ... and each possible sequence of actions on the target e-Service execution tree corresponds to possible sequences of actions on the community e-Service execution trees, **suitably interleaved**.

Example of composition

- Community *e*-Services (*expressed as FSMs*)

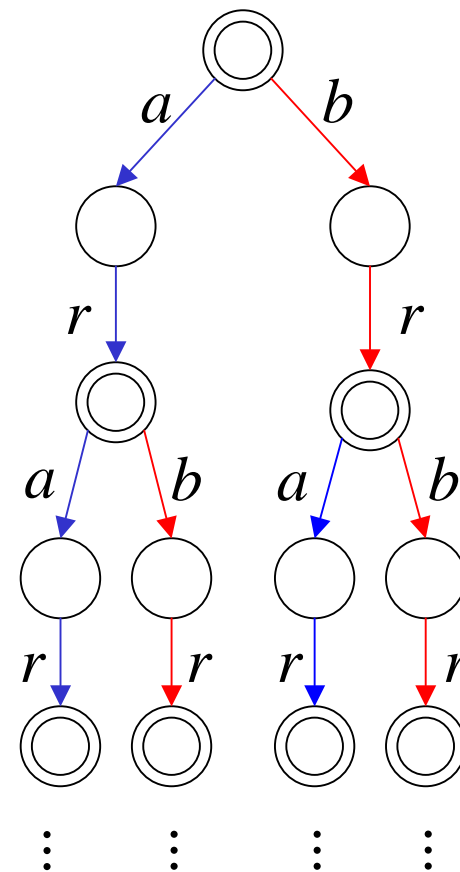
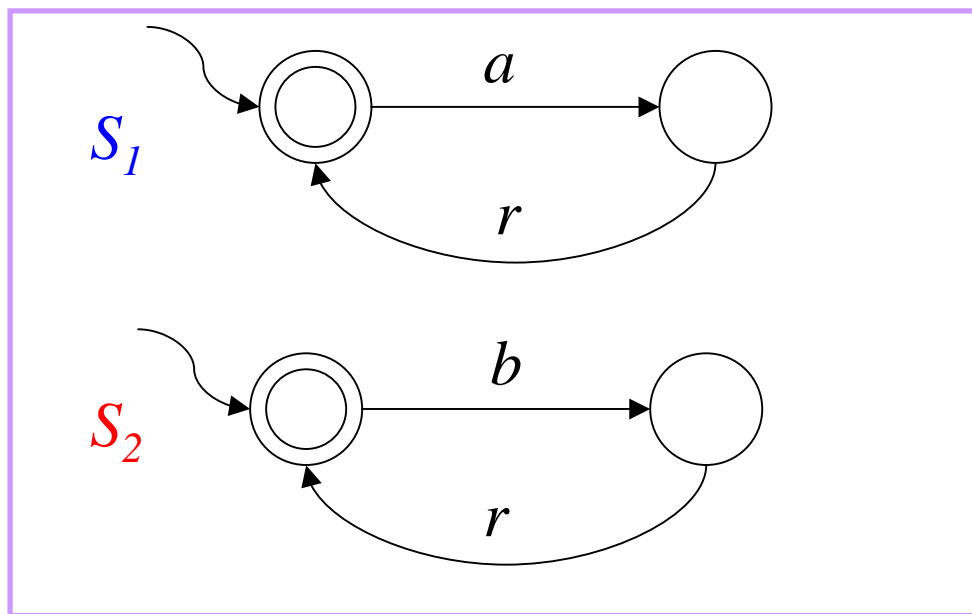
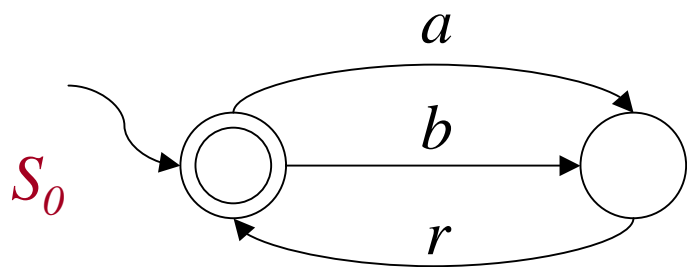


- Target *e*-Service (*again expressed as FSM*)

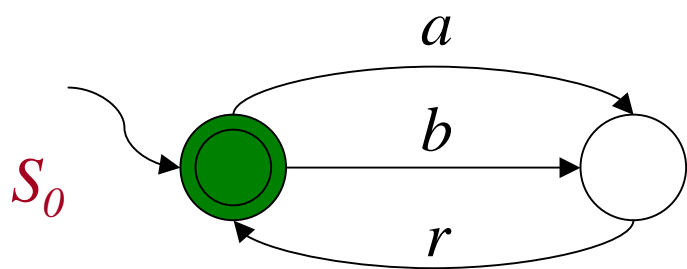


Example of composition

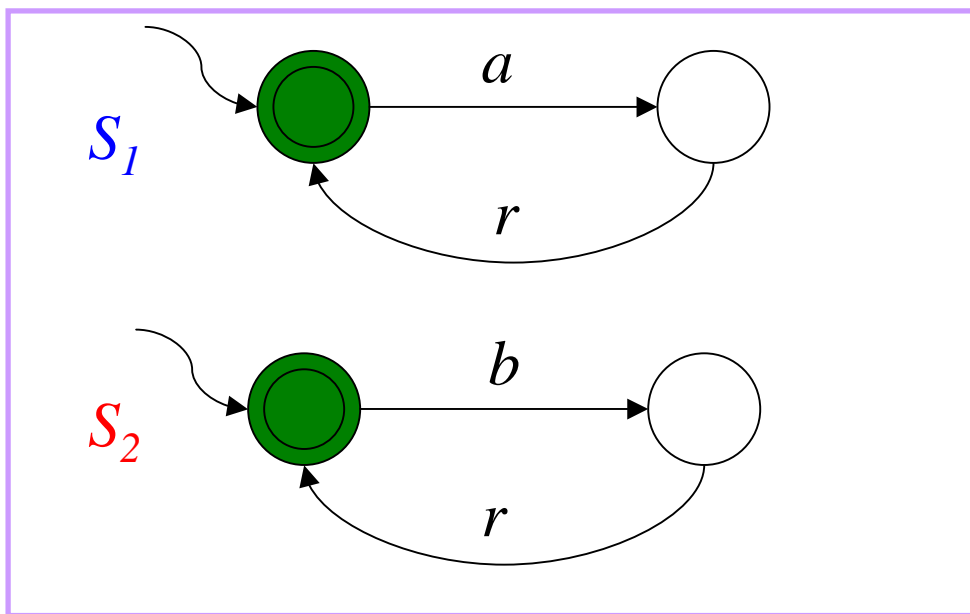
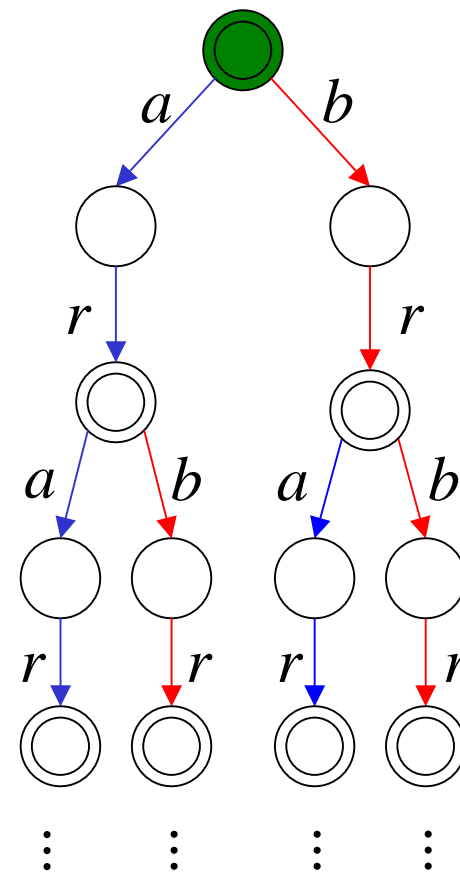
coordinating program (composition)



Example of composition



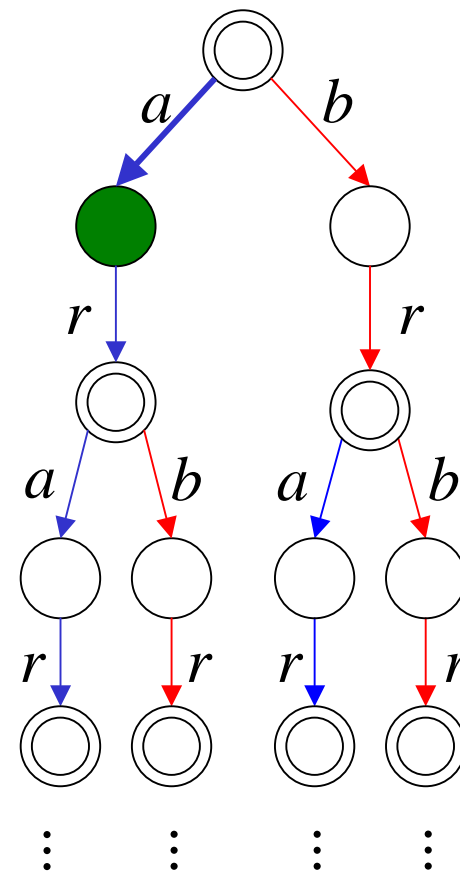
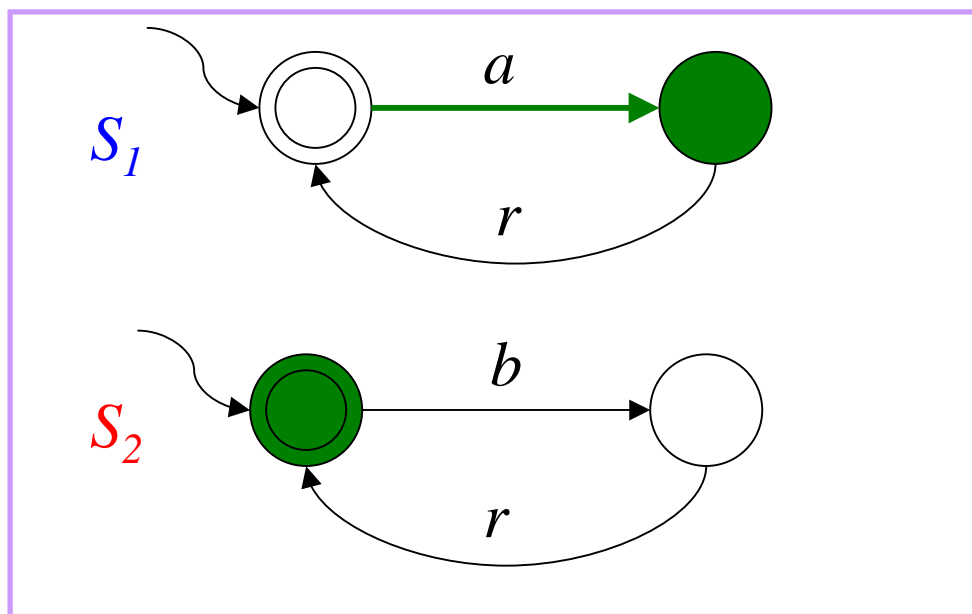
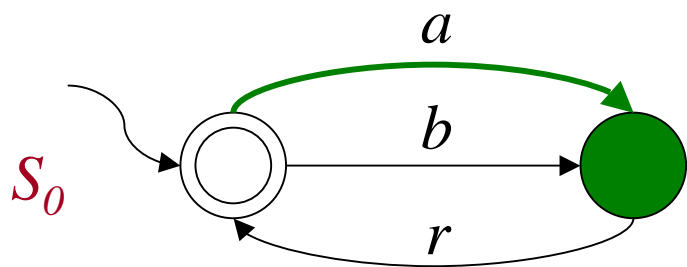
coordinating program (composition)



All e-Services start from their starting state

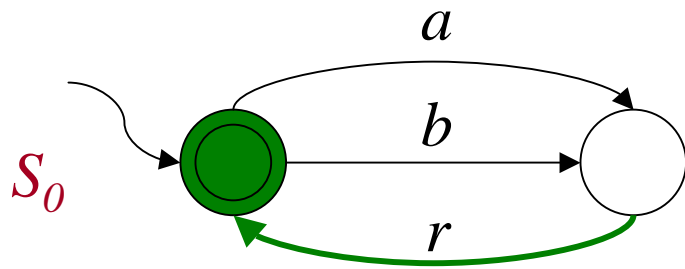
Example of composition

coordinating program (composition)

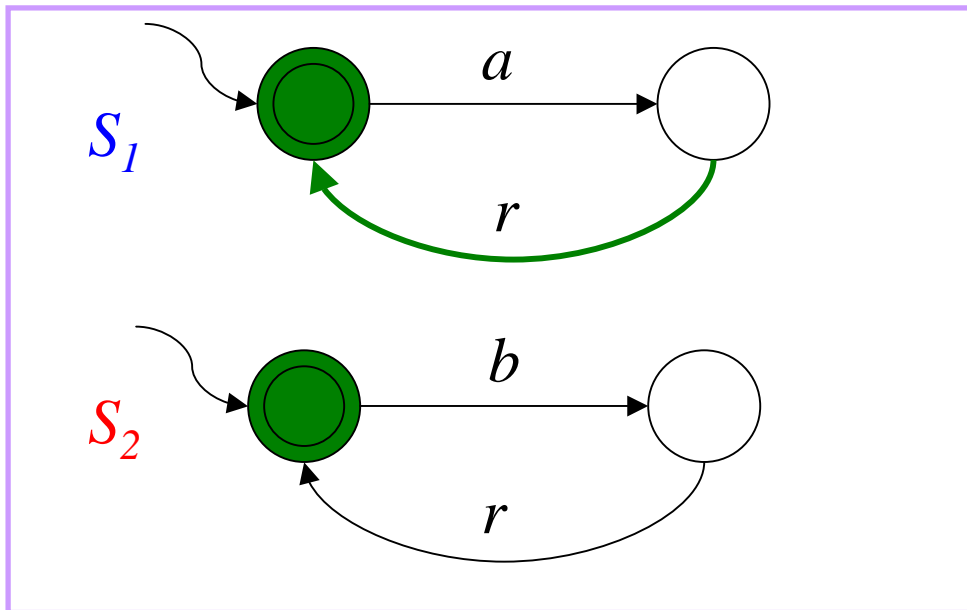
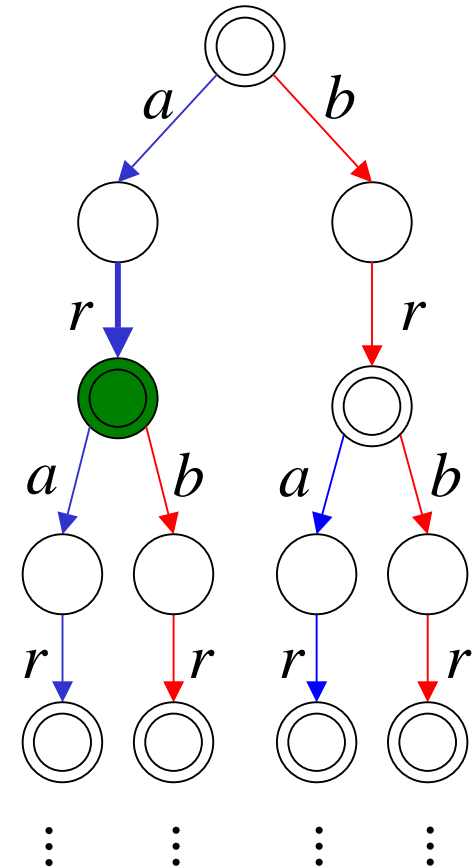


Each action of the target e-Service is executed by at least one of the component e-Services

Example of composition



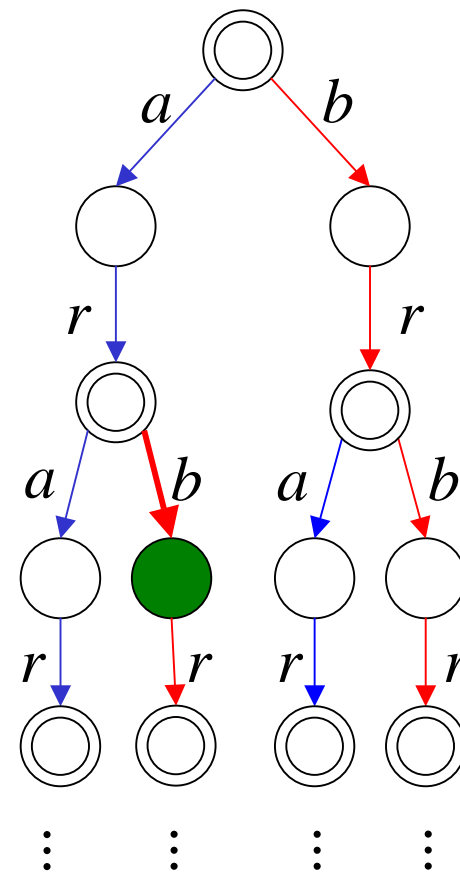
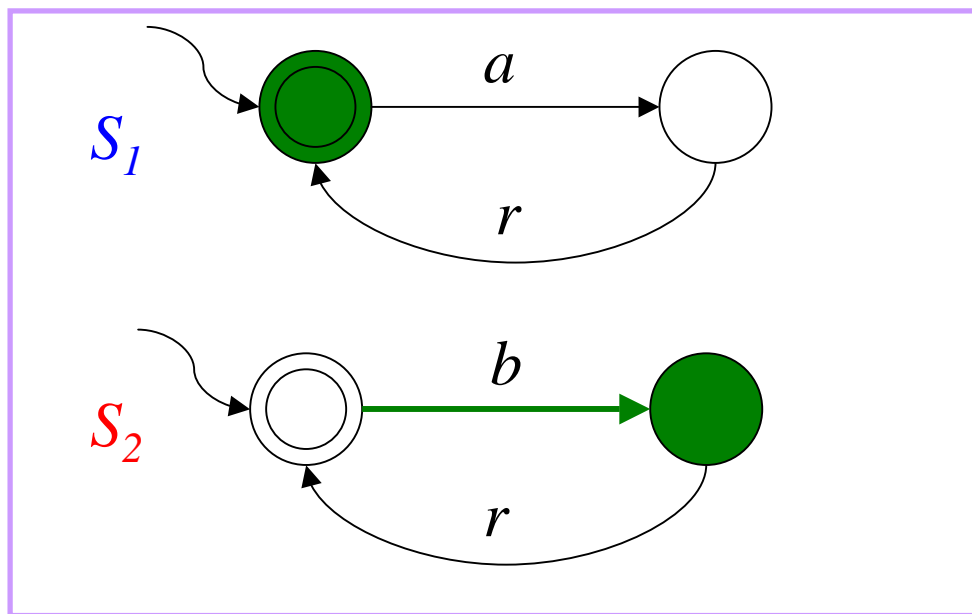
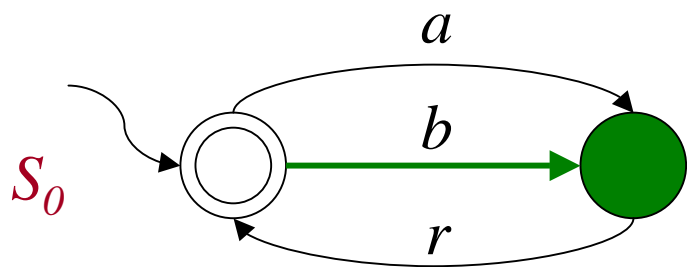
coordinating program (composition)



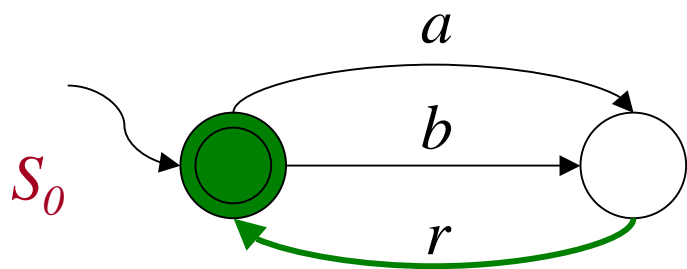
When the target e-Service can be left, then all component e-Services must be in a final state

Example of composition

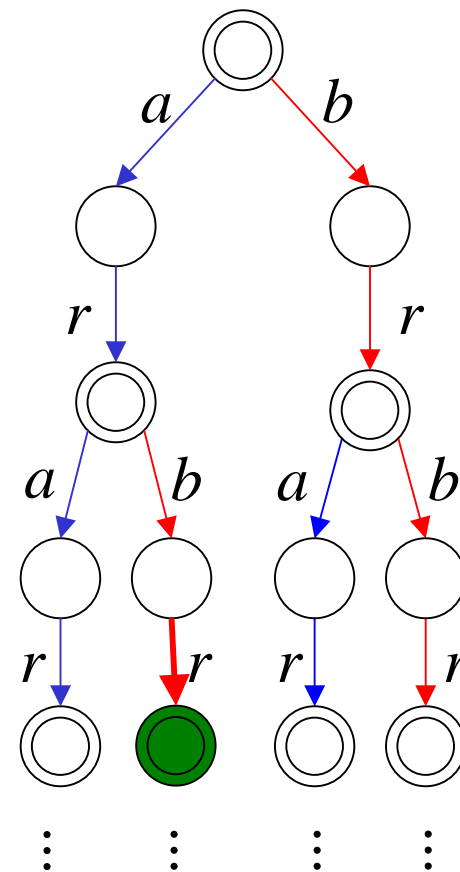
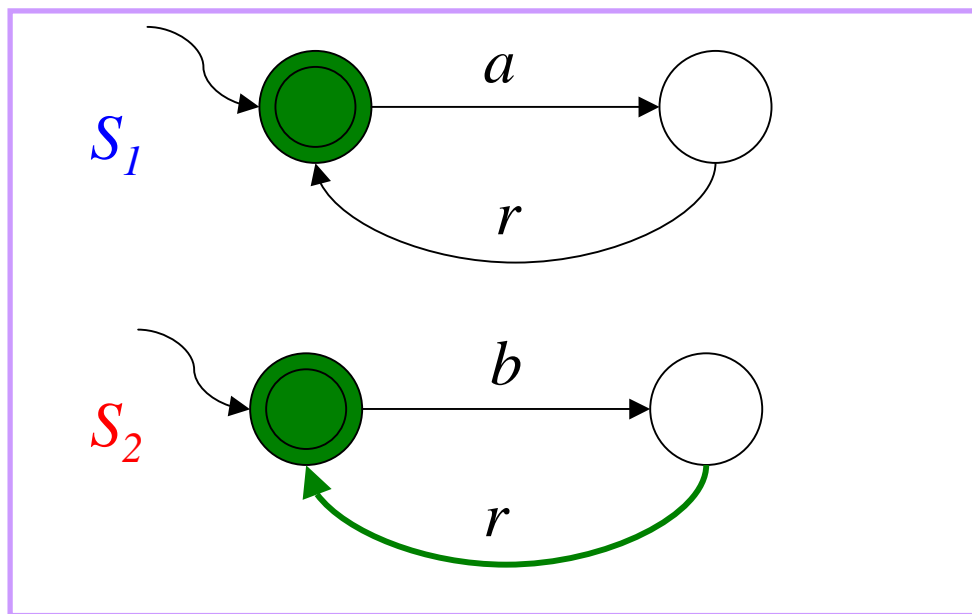
coordinating program (composition)



Example of composition

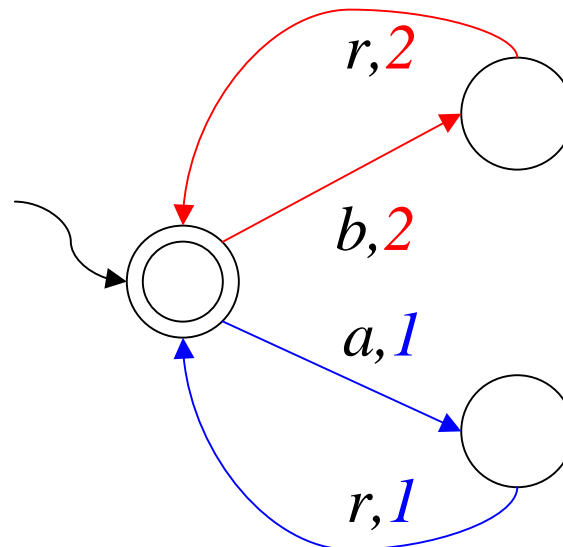


coordinating program (composition)



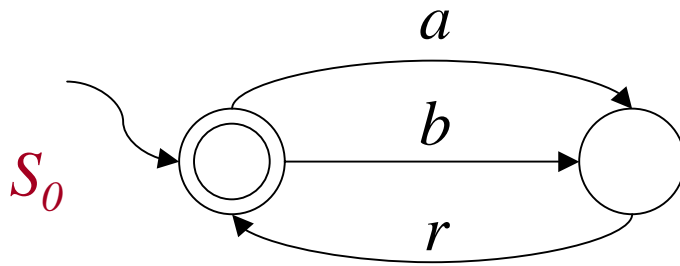
Observation

- This labeled execution tree has a finite representation as a FSM, **a Mealy machine**



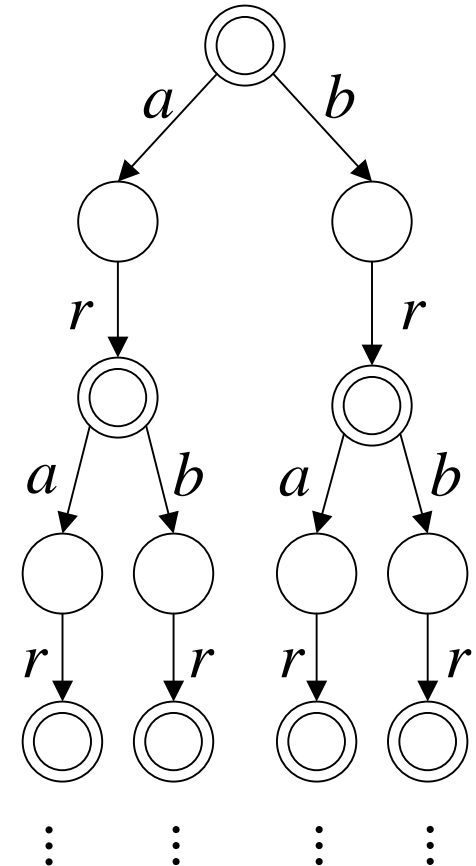
Is this always the case when we deal with e-Services expressible as FSMs? See later...

Observation



*Note: we cannot label the FSM directly ...
... we need to label the execution tree*

*Execution tree of S_0
(obtained by FSM unfolding)*



Questions

Assume *e*-Services of community and target *e*-Service are FSMs

- Can we always check composition existence?
- If a composition exists there exists one which is a Mealy machine (i.e., finite state)?
- If yes, how can a Mealy machine composition be computed?

To answer we exploit DPDL (a well-known modal logic for reasoning on program schemas)

Answers

Reduce *e*-Service composition synthesis to satisfiability in DPDL

- Can we always check composition existence?

Yes, SAT in DPDL is decidable in EXPTIME

- If a composition exists there exists one which is a Mealy machine (i.e., finite state)?

Yes, by the small model property of DPDL

- How can a Mealy machine composition be computed?

From a (small) model of the corresponding DPDL formula

DPDL encoding

$$\Phi = \text{Init} \wedge ([u]\Phi_0 \wedge_{i=1,\dots,n} [u]\Phi_i \wedge [u]\Phi_{\text{aux}})$$

Initial states of all
e-Services

DPDL encoding of
target *e*-Service

DPDL encoding of
i-th component *e*-
Service

DPDL additional
domain-
independent
conditions

DPDL encoding is polynomial in the size of the *e*-Service FSMs

DPDL encoding

- Target e-Service $S_0 = (\Sigma, S_0, s_0^0, \delta_0, F_0)$

in DPDL we define Φ_0 as the conjunction of:

- $s \rightarrow \neg s'$ for all pairs of distinct states in S_0
e-Service states are pair-wise disjoint
- $s \rightarrow \langle a \rangle T \wedge [a]s'$ for each $s' = \delta_0(s, a)$
target e-Service can do an a-transition going to state s'
- $s \rightarrow [a] \perp$ for each $\delta_0(s, a)$ undef.
target e-Service cannot do an a-transition
- $F_0 \equiv \bigvee_{s \in F_0} S$
denotes target e-Service final states

- ...

DPDL encoding (cont.d)

- Community e-Services $S_i = (\Sigma, S_i, s^0_i, \delta_i, F_i)$

in DPDL we define Φ_i as the conjunction of:

- $s \rightarrow \neg s'$ for all pairs of distinct states in S_i
e-Service states are pair-wise disjoint
- $s \rightarrow [a](\text{moved}_i \wedge s' \vee \neg \text{moved}_i \wedge s)$ for each $s' = \delta_i(s, a)$
if e-Service moved then new state, otherwise old state
- $s \rightarrow [a](\neg \text{moved}_i \wedge s)$ for each $\delta_i(s, a)$ undef.
if e-Service cannot do a, and a is performed then it did not move
- $F_i \equiv \bigvee_{s \in F_i} S$
denotes community e-Service final states

- ...

DPDL encoding (cont.d)

- Additional assertions Φ_{aux}
 - $\langle a \rangle T \rightarrow [a] \bigvee_{i=1, \dots, n} \text{moved}_i$ for each action a
at least one of the community e-Services must move at each step
 - $F_0 \rightarrow \bigwedge_{i=1, \dots, n} F_i$
when target e-Service is final all comm. e-Services are final
 - $\text{Init} \equiv s_0^0 \bigwedge_{i=1, \dots, n} s_i^0$
Initially all e-Services are in their initial state

DPDL encoding: $\Phi = \text{Init} \wedge [u](\Phi_0 \bigwedge_{i=1, \dots, n} \Phi_i \wedge \Phi_{aux})$

Results

Thm: Composition exists iff DPDL formula Φ SAT

From composition labeling of the target e-Service one can build a tree model of the DPDL formula and viceversa

Information on the labeling is encoded in predicates moved;

Composition existence of e-Services expressible as FSMs
is decidable in EXPTIME

Results on Mealy composition

Thm: If composition exists then Mealy composition exists.

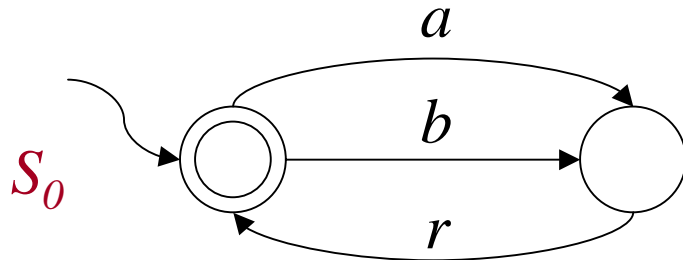
*From a small model of the DPDL formula Φ ,
one can build a Mealy machine*

*Information on the output function of the machine is encoded in
predicates moved;*

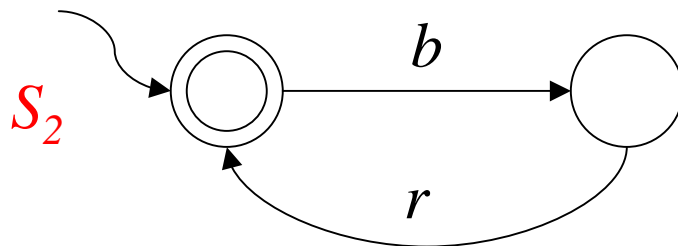
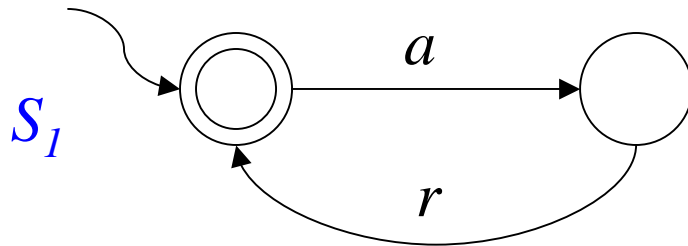
Mealy composition existence of *e*-Services expressible as
FSMs is decidable in EXPTIME

Example

Target e-Service



Community e-Services



DPDL

...

...

...

$$s_0^0 \wedge s_1^0 \wedge s_2^0$$

$$\langle a \rangle T \rightarrow [a] (\text{moved}_1 \vee \text{moved}_2)$$

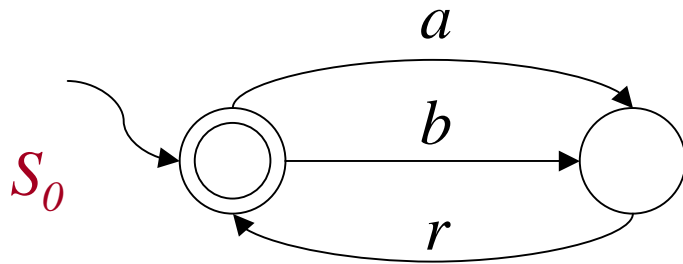
$$\langle b \rangle T \rightarrow [b] (\text{moved}_1 \vee \text{moved}_2)$$

$$\langle r \rangle T \rightarrow [r] (\text{moved}_1 \vee \text{moved}_2)$$

$$F_0 \rightarrow F_1 \wedge F_2$$

Example

Target e-Service



$$s_0^0 \rightarrow \neg s_0^1$$

$$s_0^0 \rightarrow \langle a \rangle T \wedge [a] s_0^1$$

$$s_0^0 \rightarrow \langle b \rangle T \wedge [b] s_0^1$$

$$s_0^1 \rightarrow \langle r \rangle T \wedge [r] s_0^0$$

$$s_0^0 \rightarrow [r] \perp \wedge [r] s_0^0$$

$$s_0^1 \rightarrow [a] \perp$$

$$s_0^1 \rightarrow [b] \perp$$

$$F_0 \equiv s_0^0$$

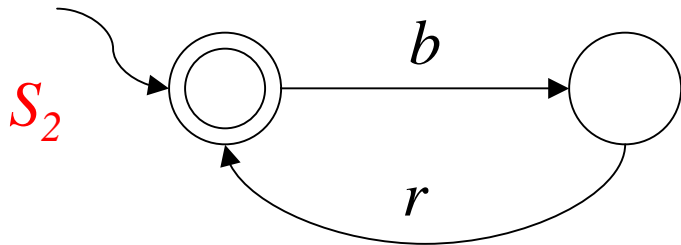
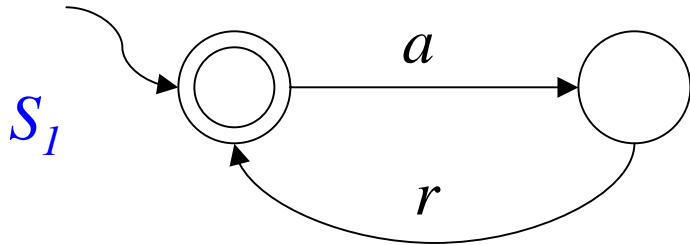
...

...

...

Example

Community e-Services



...

$$s_1^0 \rightarrow \neg s_1^1$$

$$s_1^0 \rightarrow [a] (\text{moved}_1 \wedge s_1^1 \vee \neg \text{moved}_1 \wedge s_1^0)$$

$$s_1^0 \rightarrow [r] \neg \text{moved}_1 \wedge s_1^0$$

$$s_1^0 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^0$$

$$s_1^1 \rightarrow [a] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [r] (\text{moved}_1 \wedge s_1^0 \vee \neg \text{moved}_1 \wedge s_1^0)$$

$$F_1 \equiv s_1^0$$

$$s_2^0 \rightarrow \neg s_2^1$$

$$s_2^0 \rightarrow [b] (\text{moved}_2 \wedge s_2^1 \vee \neg \text{moved}_2 \wedge s_2^0)$$

$$s_2^0 \rightarrow [r] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^0 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^1 \rightarrow [b] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [r] (\text{moved}_2 \wedge s_2^0 \vee \neg \text{moved}_2 \wedge s_2^0)$$

$$F_2 \equiv s_2^0$$

...

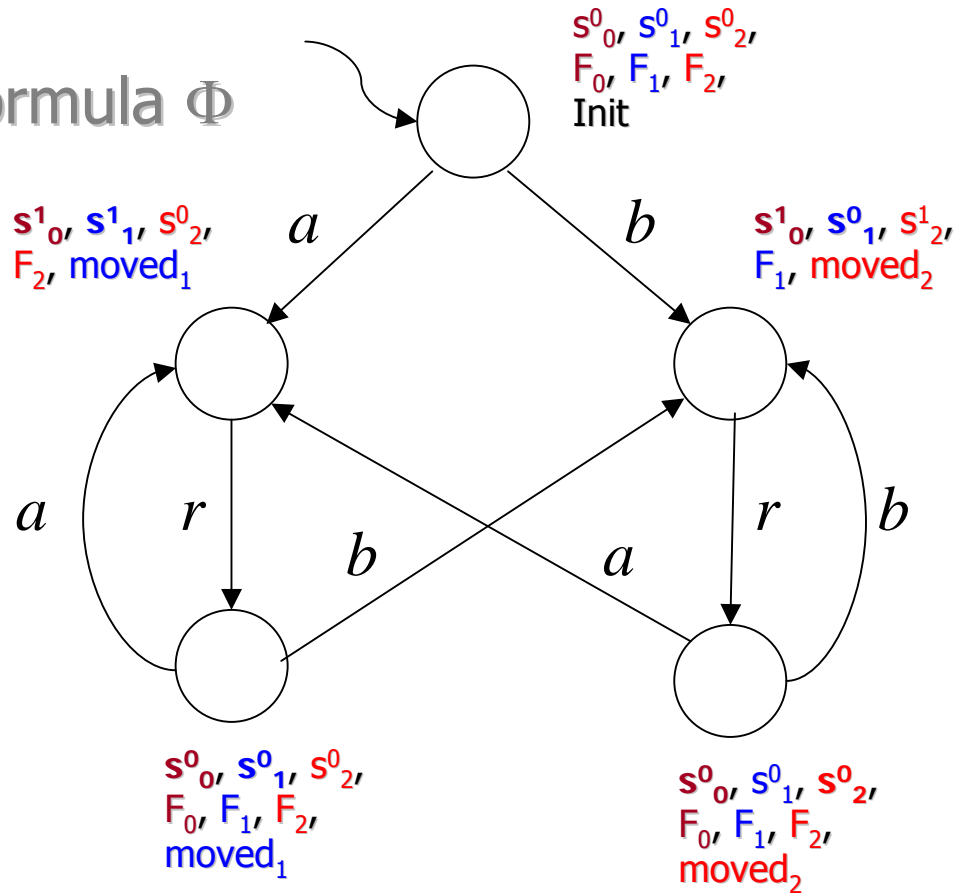
Example

Check: run SAT on DPDL formula Φ

Example

Check: run SAT on DPDL formula Φ

Yes \Rightarrow (small) model

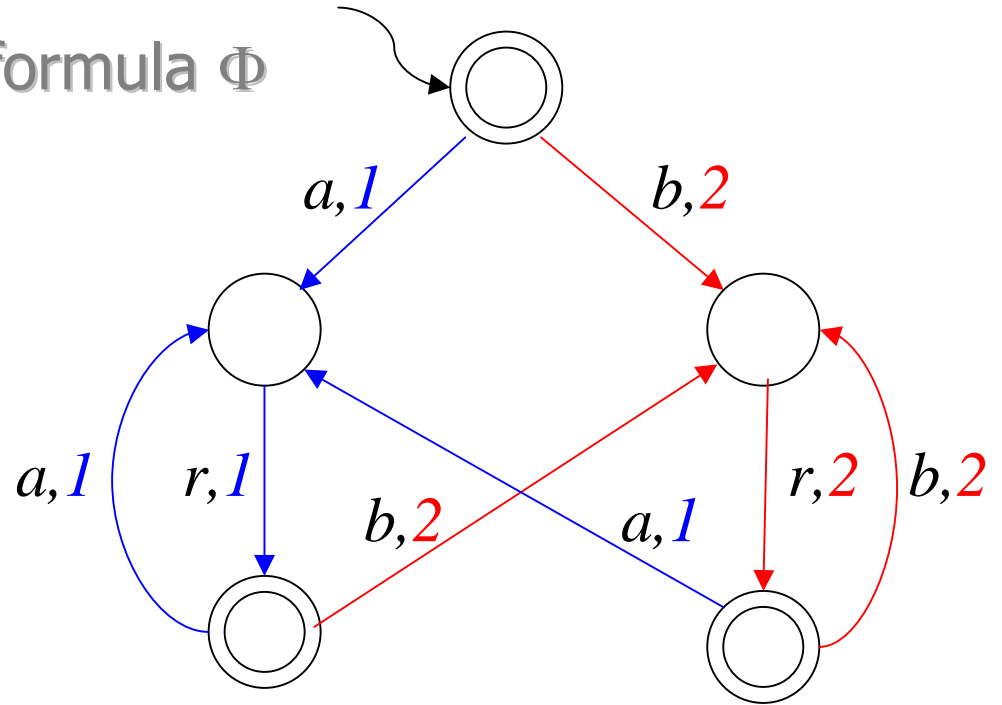


Example

Check: run SAT on DPDL formula Φ

Yes \Rightarrow (small) model

\Rightarrow extract Mealy machine



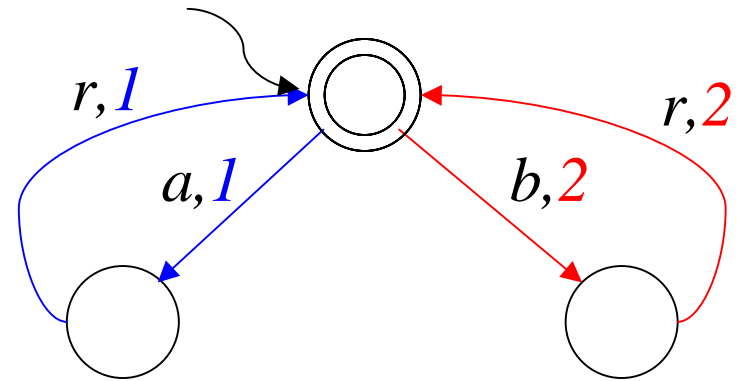
Example

Check: run SAT on DPDL formula Φ

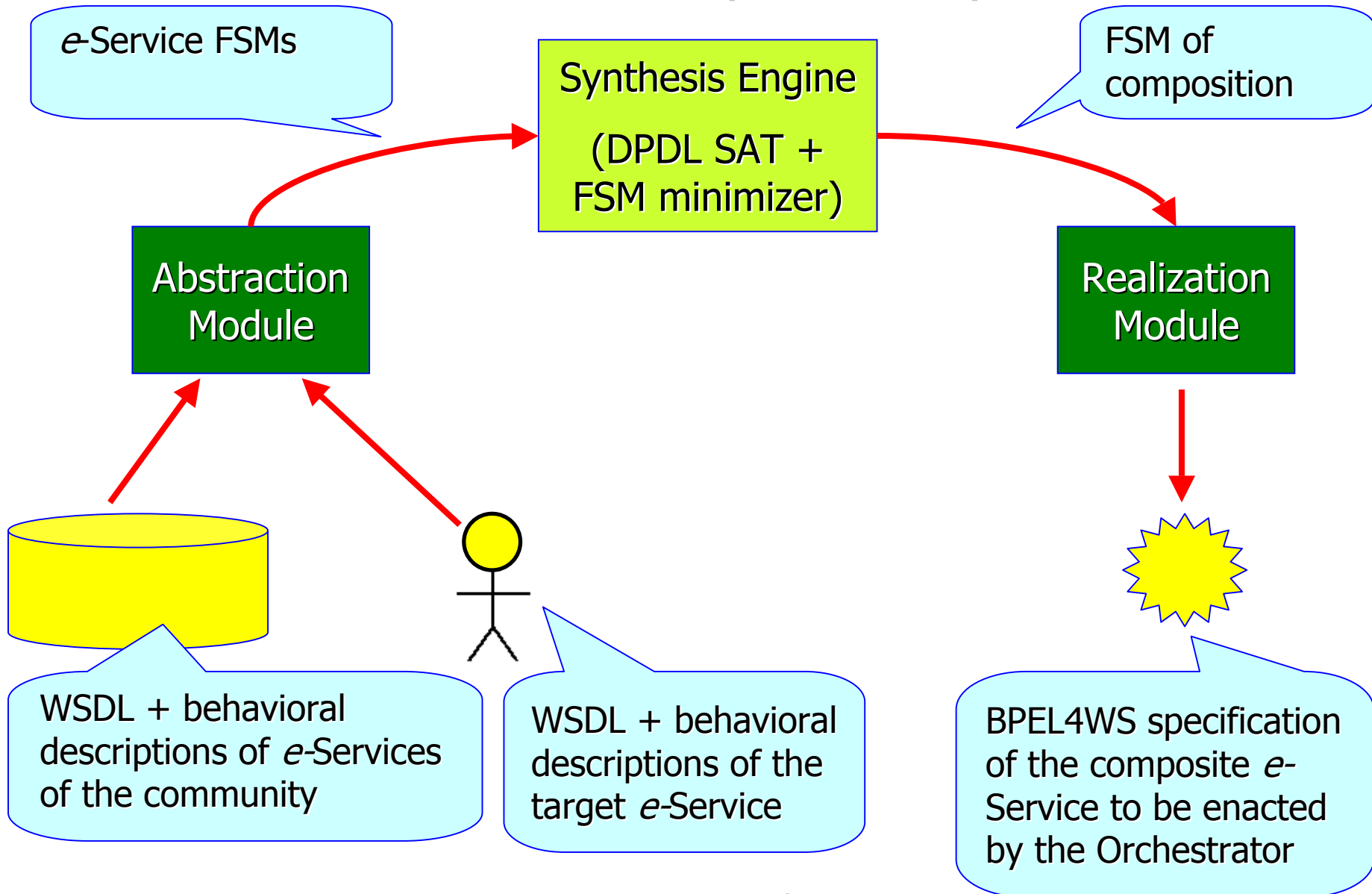
Yes \Rightarrow (small) model

\Rightarrow extract Mealy machine

\Rightarrow minimize Mealy machine



The *e*-Service Composition System



Future work

We have only scratched the surface ...

- Implementation? *We are working on it, using DPDL/DL-systems based on tableaux*
- Hardness of FSM e-Service composition?
...at least PSPACE-hard! EXPTIME-hard?
- Loose specification of target e-Service?
 - target e-Service “under-specified” *Note: angelic nondeterminism ongoing work*
- Incomplete specification of e-Services of the community?
 - e-Services export partial description of their behavior to the community
Note: synthesis with diabolic nondeterminism very hard!
- Data? ...